Validation Report

Wisconsin, SPS-1 Task Order 26, CLIN 2 May 20 and 21, 2008

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1 Executive Summary

A visit was made to the Wisconsin 0100 on May 20 and 21, 2008 for the purposes of conducting a validation of the WIM system located on SR 29, approximately 1.25 miles east of Hilltop Road. The SPS-1 is located in the righthand, westbound lane of a fourlane divided facility. The posted speed limit at this location is 65 mph. The LTPP lane is the only lane that is instrumented at this site. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This site was a relocation of an existing site located approximately 175 feet downstream from the present site. At the old site, all four lanes are instrumented with bending plate technology. The leading WIM sensor in the LTPP lane at the old site has been removed and the excavation has been filled with asphalt. This is the second validation visit to this location. The site was installed on June 19 to 20, 2007 by International Road Dynamics Inc..

This site demonstrates the ability to produce research quality loading data under the observed conditions. The classification algorithm is not currently providing research quality classification information.

The site is instrumented with bending plate WIM sensors and iSINC electronics. It is installed in portland cement concrete. This WIM location also serves to provide traffic data for the SPS-2 site, which is located immediately upstream of the SPS-1 site.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 77,520 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 68,440 lbs., the "partial" truck.

The validation speeds ranged from 52 to 65 miles per hour. The pavement temperatures ranged from 52 to 87 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was also achieved.

Table 1-1 Post-Validation results – 550100 – 21-May-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.8 \pm 3.0\%$	Pass
Tandem axles	±15 percent	$0.2 \pm 4.2\%$	Pass
GVW	±10 percent	$0.2 \pm 2.2\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	0.0 ± 0.1 ft	Pass

Prepared: djw

The pavement condition appeared to be satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions significantly. A visual survey determined that there is no discernable bouncing or avoidance by trucks in the sensor area. No profile data has been provided from which WIMIndex values can be calculated.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 Results Based on ASTM E-1318-02 Test Procedures

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

Upon our arrival at the site, we found the system parameters were the same as we left them at the conclusion of our last validation on November 28, 2007. Before Pre-Validation began, IRD remotely downloaded new firmware for the weighpad signal processing board and recommended that we install new compensation parameters that were 5% lower than the existing parameters to account for changes in weight statistics as a result of the change. The new compensation factors were installed prior to beginning Pre-Validation runs.

This site needs four years of data to meet the goal of five years of research quality data.

2 Corrective Actions Recommended

This site requires no corrective actions at this time.

3 Post Calibration Analysis

This final analysis is based on test runs conducted May 21, 2008 during the mid-morning to afternoon hours at test site 550100 on SR 29. This SPS-1 site is at milepost 189.8 on the westbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for the calibration and for the subsequent validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 77,520 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 68,440 lbs., the "partial" truck.

Each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 52 to 65 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 52 to 87 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

The statistics in Table 3-1 indicate that the loading data meets the conditions for research quality data.

Table 3-1 Post-Validation Results – 550100 – 21-May-2008

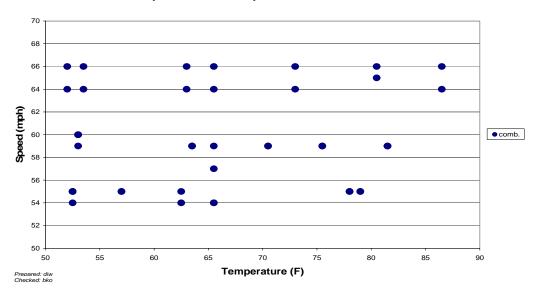
SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.8 \pm 3.0\%$	Pass
Tandem axles	±15 percent	$0.2 \pm 4.2\%$	Pass
GVW	±10 percent	$0.2 \pm 2.2\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: djw Checked: bko

The test runs were conducted primarily during the morning and afternoon hours under partly cloudy weather conditions, resulting in a range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the data set was split into three speed groups and three temperature groups. The distribution of runs by speed and temperature is illustrated in Figure 3-1. The figure indicates that the desired distribution of speed and temperature combinations was achieved for this set of validation runs.

The three speed groups were divided as follows: Low speed -52 to 56 mph, Medium speed -57 to 62 mph and High speed -63 + mph. The three temperature groups were created by splitting the runs between those at 52 to 60 degrees Fahrenheit for Low temperature, 61 to 71 degrees Fahrenheit for Medium temperature and 72 to 87 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations



Figure~3-1~Post-Validation~Speed-Temperature~Distribution~-~550100-21-May-2008

A series of graphs was developed to investigate visually any sign of a relationship between speed or temperature and the scale performance.

Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. It can be seen from the figure that the equipment estimates GVW with reasonable accuracy at all speeds. Variability in error is consistent throughout the entire speed range.

Prepared: diw Checked: bko

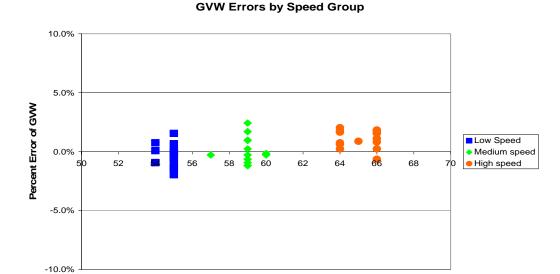


Figure 3-2 Post-validation GVW Percent Error vs. Speed – 550100 – 21-May-2008

Speed (mph)

Figure 3-3 shows the relationship between temperature and GVW percentage error. There is no apparent influence of temperature on the error estimates. Variability is consistent throughout the entire temperature range.

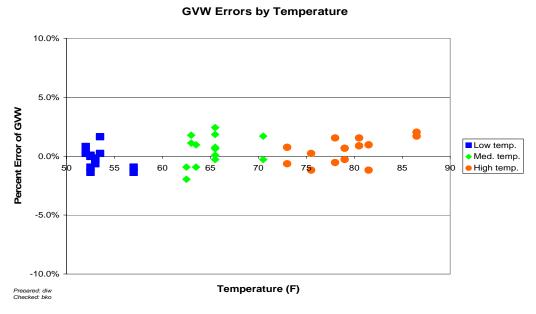


Figure 3-3 Post-Validation GVW Percent Error vs. Temperature – 550100 - 21-May-2008

Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to

correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. There is no apparent influence of speed on spacing errors. Spacing error was limited to 0.1 feet (2 inches).

Drive Tandem Spacing vs. WIM Speed

Figure 3-4 Post-Validation Spacing vs. Speed – 550100 – 21-May-2008

3.1 Temperature-based Analysis

The three temperature groups were created by splitting the runs between those at 52 to 60 degrees Fahrenheit for Low temperature, 61 to 71 degrees Fahrenheit for Medium temperature and 72 to 87 degrees Fahrenheit for High temperature.

Table 3-2 Post-Validation Results by Temperature Bin – 550100 – 21-May-2008

Element	95% Limit	Low Temperature 52 to 60 °F	Medium Temperature 61 to 71 °F	High Temperature 72 to 87 °F
Steering axles	<u>+</u> 20 %	$0.9 \pm 2.8\%$	$1.2 \pm 3.0\%$	$0.4 \pm 3.6\%$
Tandem axles	<u>+</u> 15 %	$-0.4 \pm 3.3\%$	$0.4 \pm 5.4\%$	$0.5 \pm 3.9\%$
GVW	<u>+</u> 10 %	$-0.2 \pm 1.8\%$	$0.5 \pm 2.7\%$	$0.5 \pm 2.3\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.2 \text{ ft}$	$0.0 \pm 0.2 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

From Table 3-2, it can be seen that the equipment estimates all weights at all temperatures with reasonable accuracy. Variability in error is generally consistent throughout the temperature range for all weights, with the exception of a slight increase for tandem axle weights at medium temperatures.

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph.

From the graph it can be seen that the equipment demonstrates the ability to estimate GVW for both trucks with reasonable accuracy at the observed temperatures. Variability in error for both trucks is also similar.

GVW Errors vs. Temperature by Truck

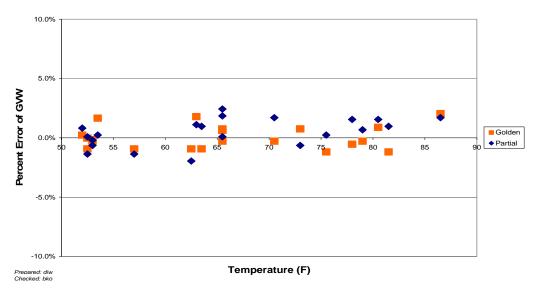


Figure 3-5 Post-Validation GVW Percent Error vs. Temperature by Truck – 550100 – 21-May-2008

Figure 3-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. Steering axle weights are generally overestimated at all temperatures. Variability appears to remain constant throughout the entire temperature range.

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Steering Axle Errors vs. Temperature

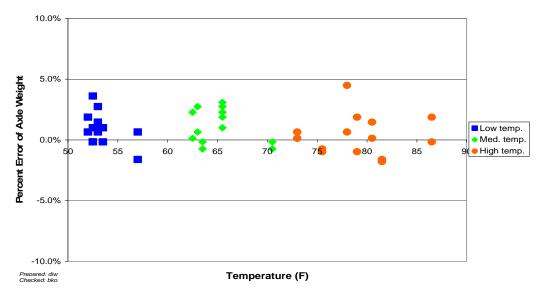


Figure 3-6 Post-Validation Steering Axle Error vs. Temperature by Group – 550100 – 21-May-2008

3.2 Speed-based Analysis

The three speed groups were divided using 52 to 56 mph for Low speed, 57 to 62 mph for Medium speed and 63+ mph for High speed.

Table 3-3 Post-Validation Results by Speed Bin – 550100 – 21-May-2008

Element	95% Limit	Low Speed 52 to 56 mph	Medium Speed 57 to 62 mph	High Speed 63+ mph
Steering axles	<u>+</u> 20 %	$1.2 \pm 3.8\%$	$0.2 \pm 3.1\%$	$1.1 \pm 2.2\%$
Tandem axles	<u>+</u> 15 %	$-0.6 \pm 3.2\%$	$0.1 \pm 4.6\%$	$1.1 \pm 4.5\%$
GVW	<u>+</u> 10 %	$-0.4 \pm 2.1\%$	$0.1 \pm 2.3\%$	$1.0 \pm 1.7\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.2 \text{ ft}$	$0.0 \pm 0.2 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

Table 3-3 demonstrates the ability of the equipment to accurately estimate all weights at all speeds. Variability is also reasonably consistent throughout the entire speed range.

From Figure 3-7, it can be seen that the equipment generally estimates GVW for both trucks accurately, with a slight overestimation at the higher speeds. Variability in error is consistent throughout the entire speed range.



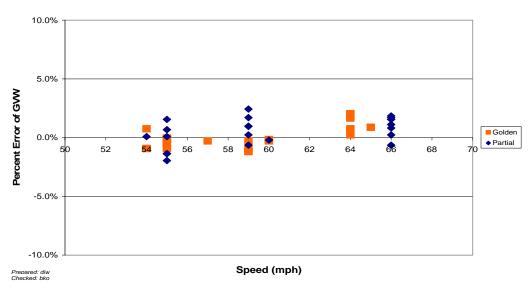


Figure 3-7 Post-Validation GVW Percent Error vs. Speed by Truck-550100-21-May-2008

Figure 3-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. From the graph, it can be seen that the equipment generally overestimates steering axle weights at all speeds. Variability appears to be slightly greater at the lower speeds.

Steering Axle Errors vs. Speed

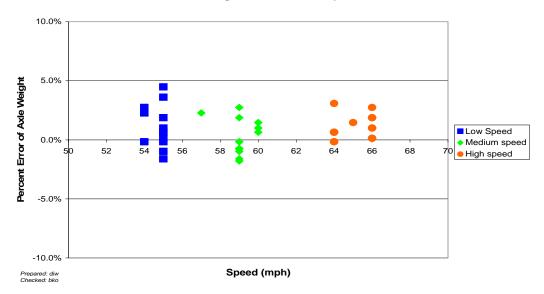


Figure 3-8 Post-Validation Steering Axle Percent Error vs. Speed by Group $-\,\,550100-21\text{-May-}2008$

3.3 Classification Validation

The agency uses a variant of the FHWA 13-bin classification scheme. Classification 15 has been added to define unclassified vehicles. A Classification 14 also exists in the output data.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 3-4 has the classification error rates by class. The overall misclassification rate is 5 percent.

Table 3-4 Truck Misclassification Percentages for 550100 – 21-May-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	0	5	14	6	0
7	0				
8	33	9	0	10	33
11	N/A	12	N/A	13	0

Prepared: djw Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 3-5 Truck Classification Mean Differences for 550100 – 21-May-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	0	5	- 14	6	0
7	0				
8	50	9	0	10	- 33
11	N/A	12	N/A	13	N/A

Prepared: djw Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown (UNK) are those identified by the equipment but no vehicles of the type were

seen by the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. Since the classification data for heavy trucks met research quality standards, with the exception of a small sample of Class 8s (4) and Class 10s (3), the observed bias and variability are thought to be more strongly related to radar speed precision than errors in the WIM equipment.

3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-6 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

4 Pavement Discussion

The pavement condition did not influence truck movement across the sensors.

4.1 Profile Analysis

Profile data collected in the year prior to the site visit or since installation do not exist. A site visit to collect profile data has not been scheduled yet. An amended report will be submitted when the data is available.

4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement no distresses that would influence truck movement across the WIM scales were noted.

4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the WIM scales. Trucks appear to track down the wheel path and daylight cannot be seen between the tires and any of the sensors for the equipment.

5 Equipment Discussion

The traffic monitoring equipment at this location includes bending plate sensors and iSINC electronics. The sensors are installed in a portland cement concrete pavement.

There were no changes in basic equipment operating condition since the validation on November 28, 2007 until the change of firmware immediately prior to the validation.

5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the evaluation. All sensors and system components were found to be within operating parameters.

5.2 Calibration Process

The equipment required one-iteration of the calibration process between the initial 40 runs and the final 40 runs.

5.2.1 Calibration Iteration 1

The operating system weight compensation parameters that were in place prior to the Pre-Validation are in Table 5-1. These are not the factors as of the end of the last validation thus the initial validation runs served as calibration inputs rather than determination of the change in loading errors since the prior validation.

Table 5-1 Initial System Parameters - 550100 - 20-May-2008

	Left	Right
Speed Bin	Sensor 1	Sensor 2
80 kph	3131	3302
88 kph	3211	3388
96 kph	3392	3579
104 kph	3114	3286
112 kph	3099	3269

Prepared: djw Checked: bko

As a result of the Pre-Validation, where the GVW error ranged from +6.7% to -1.0%, the compensation factors were adjusted as shown in Table 5-2.

Table 5-2 Calibration 1 - Change in Parameters - 550100 - 21-May-2008

1	1	T		T
		New Left Sensor		New Right Sensor
Speed Bin	Change	1 Factor	Change	2 Factor
80 kph	N/A	3131	N/A	3302
88 kph	-1.5%	3162	-1.5%	3336
96 kph	-6.7%	3164	-6.7%	3338
104 kph	+3.0%	3210	+3.0%	3386
112 kph	N/A	3099	N/A	3269

Prepared: djw

Checked: bko

Table 5-3 Calibration Iteration 1 Results – 550100 – 21-May-2008 (08:52 AM)

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.5 \pm 2.4\%$	Pass
Tandem axles	±15 percent	$-0.4 \pm 3.6\%$	Pass
GVW	±10 percent	$-0.2 \pm 1.7\%$	Pass
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.2 \text{ ft}$	Pass

Prepared: djw Checked: bko

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As shown in Table 5-3 and Figure 5-1, the calibration produced the expected results. No additional calibration iterations of the equipment were required.

GVW Errors by Speed Group 10.0% 5.0% Percent Error of GVW Low Speed 0.0% Medium speed 52 62 64 66 68 High speed -5.0% -10.0% Speed (mph)

Figure 5-1 Calibration Iteration 1 GVW Percent Error vs. Speed Group – 550100 – 21-May-2008 (08:52 AM)

5.3 Summary of Traffic Sheet 16s

This site has validation information from the previous visit as well as the current one in the tables below. Sheet 16 data for previous equipment installations is not included.

Table 5-4 has the information for TRF_CALIBRATION_AVC for Sheet 16s submitted prior to this validation as well as the information for the current visit. The Sheet 16s available reflect only this contractor's validation visits.

Table 5-4 Classification Validation History – 550100 – 21-May-2008

Date	Method		Mean Difference			Percent
		Class 9 Class 8 Class 5 Other 2				Unclassified
21-May-08	Manual	0		-14		1.0
20-May-08	Manual	-1		-15		2.0
28-Nov-07	Manual	0	0			0.0
27-Nov-07	Manual	0	0			0.0

Prepared: djw Checked: i

Table 5-5 has the information for TRF_CALIBRATION_WIM for Sheet 16s submitted prior to this validation as well as the information for the current visit. The Sheet 16s available reflect only this contractor's validation visits.

Table 5-5 Weight Validation History – 550100 – 21-May-2008

Date	Method	Mean Error and (SD)		
		GVW	Single Axles	Tandem Axles
21-May-08	Test Trucks	0.2 (1.1)	0.8 (1.5)	0.2 (2.1)
20-May-08	Test Trucks	3.2 (3.6)	4.7 (3.7)	2.9 (3.9)
28-Nov-07	Test Trucks	-0.5 (2.8)	-2.0 (3.7)	-0.2 (3.9)
27-Nov-07	Test Trucks	-1.8 (3.2)	-5.4 (3.7)	-1.0 (4.1)

Prepared: djw Checked: bko

5.4 Projected Maintenance/Replacement Requirements

This site is scheduled for semi-annual maintenance under the installation contract.

6 Pre-Validation Analysis

Upon our arrival at the site, we found the system parameters were the same as we left them at the conclusion of our last validation on November 28, 2007. Before Pre-Validation began, IRD remotely downloaded new firmware for the weighpad signal processing board. They recommended that we install new compensation parameters that were 5% lower than the existing parameters to account for changes in weight statistics as a result of the change. The parameter changes were made in accordance with their recommendations. Those factors and the changes installed following IRD's firmware upgrade prior to the Pre-validation are shown Table 6-1:

Table 6-1 Weight Compensation Factor Changes Made Following Firmware Change - 550100 - 20-May-2008

	Left / S	Sensors 1	Right / Sensors 2		
	20-May-2008	28-Nov-2007	20-May-2008	28-Nov-2007	
80 kph	3131	3296	3302	3476	
88 kph	3211	3381	3388	3566	
96 kph	3392	3571	3579	3767	
104 kph	3114	3278	3286	3459	
112 kph	3099	3262	3269	3441	

Prepared: djw

The Pre-Validation analysis is based on test runs conducted May 20, 2008 during the morning and early afternoon hours at test site 550100 on SR 29. This SPS-1 site is at milepost 189.8 on the westbound, righthand of a four-lane divided facility. No autocalibration was used during test runs. The two trucks used for initial validation included:

- 1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 76,870 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 68,150 lbs., the "partial" truck.

For the initial validation each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 50 to 65 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 67 to 97degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was also achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-2.

Table 6-2 indicates that due to variability in GVW error, the conditions for research quality loading data were not met following the changes applied after the firmware installation.

Table 6-2 Pre-Validation Results – 550100 – 20-May-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	+20 percent	$4.7 \pm 7.4\%$	Pass
Tandem axles	±15 percent	$2.9 \pm 7.8\%$	Pass
GVW	±10 percent	$3.2 \pm 7.3\%$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.2 \text{ ft}$	Pass

Prepared: djw Checked: bko

The test runs were conducted primarily during the morning and early afternoon hours under mostly sunny weather conditions, resulting in a range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and two temperature groups. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired distribution of speed and temperature combinations was achieved for this set of validation runs.

The three speed groups were divided into 50 to 56 mph for Low speed, 57 to 62 mph for Medium speed and 63+ mph for High speed. The two temperature groups were created by splitting the runs between those at 67 to 80 degrees Fahrenheit for Low temperature and 81 to 97 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations

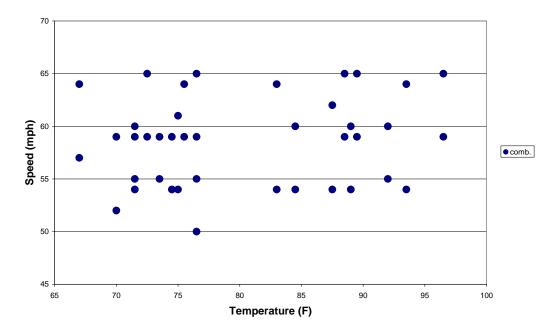


Figure 6-1 Pre-Validation Speed-Temperature Distribution – 550100 – 20-May-2008

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. As can be seen in the figure, the system increasingly overestimates GVW from the lower speeds to the medium speeds and then moves toward an underestimation at the higher speeds. Error is greater at the medium speeds when compared with low and high speeds. Variability appears to be greatest at the medium speeds.

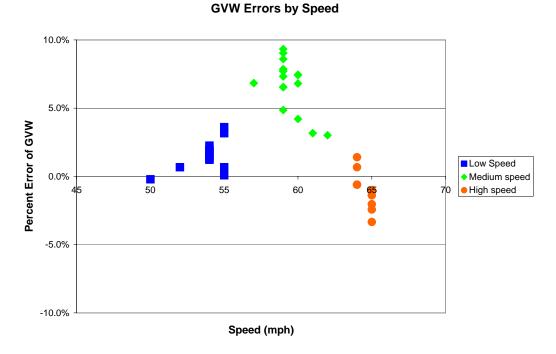


Figure 6-2 Pre-validation GVW Percent Error vs. Speed – 550100 – 20-May-2008

Figure 6-3 shows the relationship between temperature and GVW percentage error. The graph shows that GVW is overestimated at all temperatures. Variability appears to remain consistent over the entire temperature range.

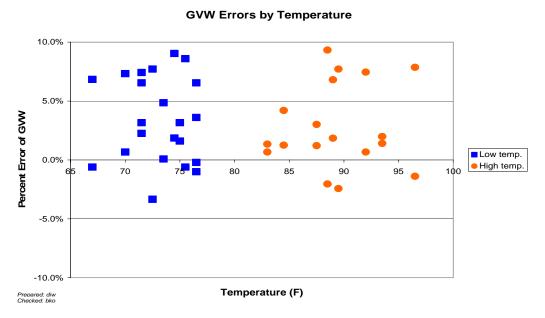


Figure 6-3 Pre-Validation GVW Percent Error vs. Temperature – 550100 – 20-May-2008

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. There is no apparent influence of speed on spacing error, which are limited to 0.1 feet (2 inches).

Drive Tandem Spacing vs. WIM Speed

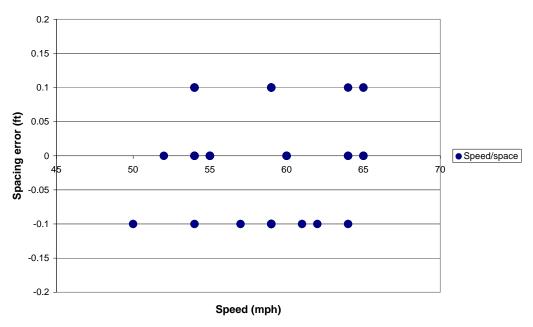


Figure 6-4 Pre-Validation Spacing vs. Speed - 550100 – 20-May-2008

6.1 Temperature-based Analysis

The two temperature groups were created by splitting the runs between those at 67 to 80 degrees Fahrenheit for Low temperature and 81 to 97 degrees Fahrenheit for High temperature.

Table 6-3 Pre-Validation Results by Temperature Bin – 550100 – 20-May-2008

Element	95% Limit	Low Temperature 67 to 80 °F	High Temperature 81 to 97 °F
Steering axles	<u>+</u> 20 %	$5.3 \pm 7.7\%$	$4.0 \pm 7.6\%$
Tandem axles	<u>+</u> 15 %	$3.1 \pm 8.1\%$	$2.6 \pm 7.8\%$
GVW	<u>+</u> 10 %	$3.4 \pm 7.6\%$	$2.8 \pm 7.6\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.2 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

From Table 6-3, it can be seen that the equipment produces an overestimation of all weights at all temperatures. For all weights, variability appears to be consistent throughout the entire temperature range.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck. As can be seen in the graph, the equipment generally overestimates the GVW for both trucks at all temperatures. The error and variability for both trucks is similar.

GVW Errors vs. Temperature by Truck

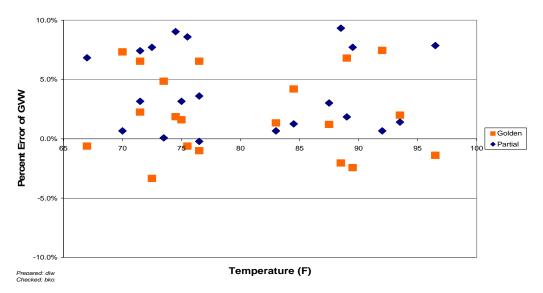


Figure 6-5 Pre-Validation GVW Percent Error vs. Temperature by Truck – 550100 – 20-May-2008

Figure 6-6 shows the relationship between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for auto-calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. At all temperatures, the steering axle weights are generally overestimated. Variability in error is consistent throughout the entire temperature range.



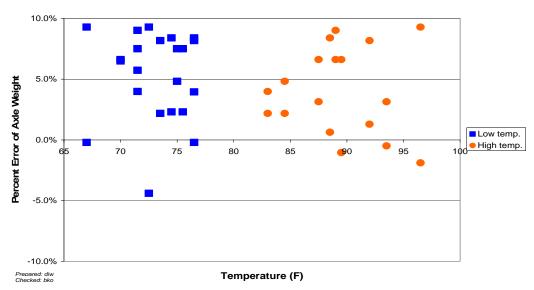


Figure 6-6 Pre-Validation Steering Axle Error vs. Temperature by Group – 550100 – 20-May-2008

6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed -50 to 56 mph, Medium speed -57 to 62 mph and High speed -63+ mph.

Table 6-4 Pre-Validation Results by Speed Bin – 550100 – 20-May-2008

Element	95% Limit	Low Speed 50 to 56 mph	Medium Speed 57 to 62 mph	High Speed 63+ mph
Steering axles	<u>+</u> 20 %	$4.2 \pm 4.4\%$	$7.9 \pm 2.6\%$	$-0.3 \pm 4.7\%$
Tandem axles	<u>+</u> 15 %	$1.1 \pm 3.1\%$	$6.5 \pm 5.7\%$	$-1.2 \pm 3.8\%$
GVW	<u>+</u> 10 %	$1.5 \pm 2.3\%$	$6.7 \pm 4.0\%$	$-1.0 \pm 3.4\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.2 \text{ ft}$	$0.0 \pm 0.2 \text{ ft}$

Prepared: djw Checked: bko

Table 6-4 shows the tendency for the equipment to overestimate all weights at the low and medium speeds, and underestimate all weights at the higher speeds. Variability in error for steering axle appears to decrease at the medium speeds when compared with low and high speeds, while tandem axle and GVW error appears to display an opposing trend.

As can be seen in Figure 6-7, the weight estimation and error variability patterns of the two trucks appear similar at all speeds.

GVW Errors vs. Speed

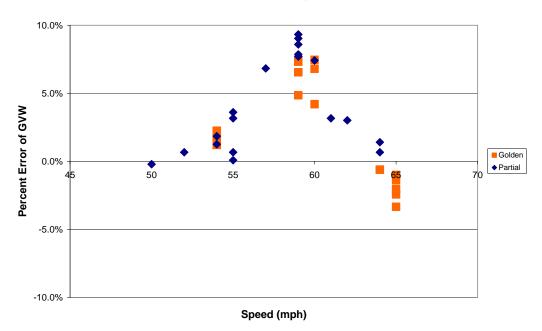


Figure 6-7 Pre-Validation GVW Percent Error vs. Speed Group - 550100 –20-May-2008

Figure 6-8 shows the relation between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. The figure illustrates the tendency for the equipment to increasingly overestimate steering axle weights from low to medium speeds and then transition to an underestimation at the higher speeds. Variability in error appears to be greater at the lower speeds when compared with medium and high speeds.

Steering Axle Errors vs. Speed

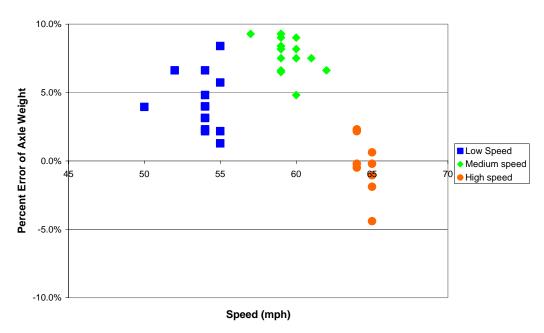


Figure 6-8 Pre-Validation Steering Axle Percent Error vs. Speed Group - 550100 – 20-May-2008

6.3 Classification Validation

The agency uses a variant of the FHWA 13-bin classification scheme. Classification 15 has been added to define unclassified vehicles. A Classification 14 also appears in the output data files.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-5 has the classification error rates by class. The overall misclassification rate is 8 percent.

Table 6-5 Truck Misclassification Percentages for 550100 – 20-May-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	67	5	23	6	0
7	0				
8	13	9	1	10	33
11	N/A	12	N/A	13	N/A

Prepared: djw

Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 6-6 Truck Classification Mean Differences for 550100 – 20-May-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	50	5	- 15	6	0
7	0				
8	14	9	- 1	10	- 33
11	N/A	12	N/A	13	N/A

Prepared: djw Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. Since the classification data for heavy trucks met research quality standards, with the exception of a small sample of Class 8s (7) and Class 10s (3), the observed bias and variability are thought to be more strongly related to radar speed precision than errors in the WIM equipment.

6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-7 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

6.5 Prior Validations

The last validation for this site was done November 27 and 28, 2007. It was the first validation of the site. The site was producing research quality data. Figure 6-9 shows the GVW Percent Error vs. Speed for the post validation runs. The site was validated with two trucks. The "Golden" truck was loaded to 77,530 lbs. The "partial" truck which had air suspension on both tandems was loaded to 68,170 lbs. The greater variability observed in the Pre-Validation runs for medium speeds existed then as well.

GVW Errors by Speed Group

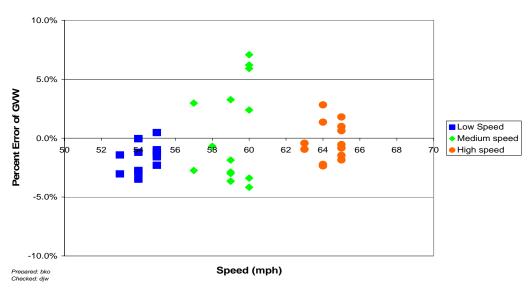


Figure 6-9 Last Validation GVW Percent Error vs. Speed – 550100 – 28-Nov-2007

Table 6-8 shows the overall results from the last validation. The site was left with a tendency to slightly underestimate tandem axle and gross vehicle weights.

Table 6-8 Last Validation Final Results – 550100 – 28-Nov-2007

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$-2.0 \pm 7.5\%$	Pass
Tandem axles	±15 percent	$-0.2 \pm 7.7\%$	Pass
Gross vehicle weights	±10 percent	$-0.5 \pm 5.6\%$	Pass
Axle spacing	+ 0.5 ft [150 mm]	$0.0 \pm 0.0 \text{ ft}$	Pass

Prepared: djw

Checked: bko

Table 6-9 has the results at the end of the last validation by temperature. The variability at both the very cold and very warm ends of the observed temperature range is very similar. Through this validation the equipment has been observed at temperature from 12 to 97 degrees Fahrenheit.

Table 6-9 Last Validation Results by Temperature Bin – 550100 – 28-Nov-2007

Element	95% Limit	Low Temperature 12 to 22 °F	High Temperature 23 to 30 °F
Steering axles	<u>+</u> 20 %	$-1.7 \pm 7.1\%$	$-2.3 \pm 8.3\%$
Tandem axles	<u>+</u> 15 %	$-0.3 \pm 6.8\%$	$-0.1 \pm 8.6\%$
GVW	<u>+</u> 10 %	$-0.6 \pm 5.8\%$	$-0.5 \pm 5.9\%$
Axle spacing	<u>+</u> 0.5 ft	$-0.1 \pm 0.1 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$

Table 6-10 has the results of the prior post validation by speed groups. The downward trend for steering axle estimates with increasing speed and the slight rise in the estimates at the medium speeds for tandem axles and GVW was present then as well.

Table 6-10 Last Validation Results by Speed Bin – 550100 – 28-Nov-2007

Element	95% Limit	Low Speed 53 to 55 mph	Medium Speed 56 to 61 mph	High Speed 62+ mph
Steering axles	<u>+</u> 20 %	$-3.7 \pm 3.9\%$	-1.5 ± 11.6%	$-0.9 \pm 4.1\%$
Tandem axles	<u>+</u> 15 %	$-1.3 \pm 4.0\%$	$0.7 \pm 11.5\%$	$-0.1 \pm 4.9\%$
GVW	<u>+</u> 10 %	$-1.6 \pm 2.7\%$	$0.1 \pm 8.7\%$	$-0.2 \pm 3.6\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.0 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

7 Data Availability and Quality

As of May 20, 2008 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

The amount and coverage for the site for years prior to installation is not included in this report. There is insufficient data in any year (1998, 1999, 2000 and 2001) to qualify for research quality data. In the absence of data from the previous

page 26

installation, it can be seen that at least four additional years of research quality data are needed to meet the goal of a minimum of 5 years of research weight data.

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Only Class 9s constitute more than 10 percent of the truck population. Based on the data collected following this validation the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the Regional Support Contractor on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-1 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-1 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.
- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

Table 7-1 GVW Characteristics of Major sub-groups of Trucks – 550100 – 21-May-2008

Characteristic	Class 9
Percentage Overweights	0.0%
Percentage Underweights	0.6%
Unloaded Peak	36,000 lbs
Loaded Peak	80,000 lbs

Prepared: djw Checked: bko

The expected percentage of unclassified vehicles is 0.2%. This is based on the percentage of unclassified vehicles (Class 15) in the Post-Validation data download.

The graphical screening comparison figures are found in Figure 7-1 through Figure 7-3. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the Post-Validation period.

Class 9 GVW Distribution

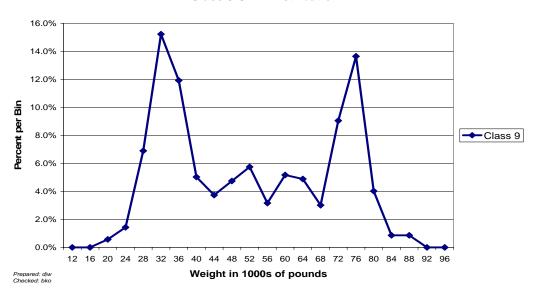


Figure 7-1 Expected GVW Distribution Class 9 – 550100 – 21-May-2008

18.0% 16.0% 14.0% Percent of Truck Population 12.0% 10.0% ---Class 8.0% 6.0% 4.0% 2.0% 0.0% 5 12 13 14 15 **Vehicle Classification**

Figure 7-2 Expected Vehicle Distribution – 550100 – 21-May-2008

Vehicle Distribution Trucks (4-15)

Speed Distribution For Trucks

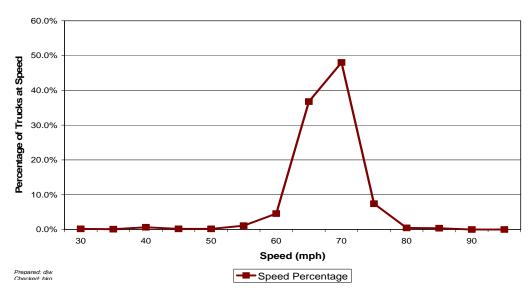


Figure 7-3 Expected Speed Distribution – 550100 – 21-May-2008

8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

Sheet 19 - Truck 1 - 3S2 loaded air suspension (3 pages)

Sheet 19 – Truck 2 – 3S2 partially loaded air suspension (3 pages)

Sheet 20 – Speed and Classification verification – Pre-Validation (2 pages)

Sheet 20 – Speed and Classification verification – Post-Validation (2 pages)

Sheet 21 – Pre-Validation (3 pages)

Sheet 21 – Calibration Iteration 1 – (1 page)

Sheet 21 – Post-Validation (2 pages)

Calibration Iteration 1 Worksheets – (1 page)

Test Truck Photographs (6 pages)

LTPP Mod 3 Classification Scheme (1 page)

Final System Parameters (1 page)

9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following the end of this report. It includes a current Sheet 17 with all applicable maps and photographs. There are no significant changes in the information provided.

10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

11 Traffic Sheet 16(s)

Sheet 16s for the pre-validation and post-validation conditions are attached following the current Sheet 18 information at the very end of the report.

POST-VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

STATE: Wisconsin

SHRP ID: 550100

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Photo 5 - 55_0100_Cabinet_Exterior_05_20_08.jpg	
Photo 6 - 55_0100_Cabinet_Interior_Front_05_20_08.jpg	
Photo 7 - 55_0100_Cabinet_Interior_Back_05_20_08.jpg	
Photo 8 - 55_0100_Leading_WIM_Sensor_05_20_08.jpg	
Photo 9 - 55_0100_Trailing_WIM_Sensor_05_20_08.jpg	
Photo 10 - 55_0100_Leading_loop_05_20_08.jpg	
Photo 11 - 55 0100 Trailing Loop 05 20 08.jpg	

Validation – WI 0100 Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites

1. General Information

SITE ID: 550100

LOCATION: State Highway 29, milepost 189.8.

VISIT DATE: May 20, 2008

VISIT TYPE: Validation

2. Contact Information

POINTS OF CONTACT:

Validation Team Leader: Dean J. Wolf, 301-210-5105, djwolf@mactec.com

Highway Agency: Laura Fenley, 608-246-5455, <u>laura.fenley@dot.state.wi.us</u>

Bill Duckert, 608-246-5440, william.duckert@dot.state.wi.us

Steven Krebs, 608-246-5399, steven.krebs@dot.state.wi.us

John Williamson, 608-267-2939, john.williamson@dot.state.wi.us

FHWA COTR: Debbie Walker, 202-493-3068, deborah.walker@fhwa.dot.gov

FHWA Division Office Liaison: Wesley Shemwell, 608-829-7521,

Wesley.shemwell@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm

3. Agenda

BRIEFING DATE: Briefing not requested for this visit

ON SITE PERIOD: Beginning May 20, 2008

TRUCK ROUTE CHECK: Verified last visit

4. Site Location/ Directions

NEAREST AIRPORT: Central Wisconsin Airport, Wausau/Stevens Point, Wisconsin.

DIRECTIONS TO THE SITE: State Highway 29, 1.25miles east of Hilltop Road.

MEETING LOCATION: On site beginning at 9:00 a.m.

WIM SITE LOCATION: US Route 29, milepost 189.8 (Latitude: 44.8508 of and

Longitude: -89.2671⁰)

WIM SITE LOCATION MAP:



Figure 4-1 Site 550100 in Wisconsin

5. Truck Route Information

ROUTE RESTRICTIONS: None.

SCALE LOCATION: *Rib Mountain Travel Center (BP station), US 51/SR-29 Exit 188 Wausau, WI; Phone: 715-355-5600, Fax: 715-359-8728, Proprietor: Sharon Klatt; Latitude: 44.91512, Long: -89.64942; Open 24/7; \$8.50 per weigh.*

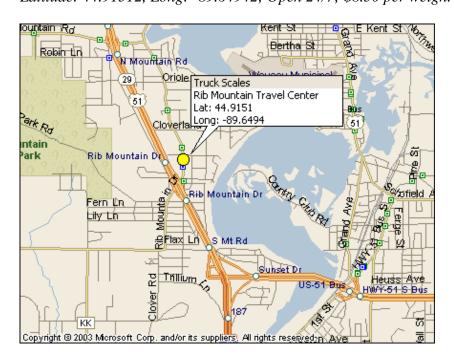


Figure 5-1 - Truck Scale Location - 550100

TRUCK ROUTE:

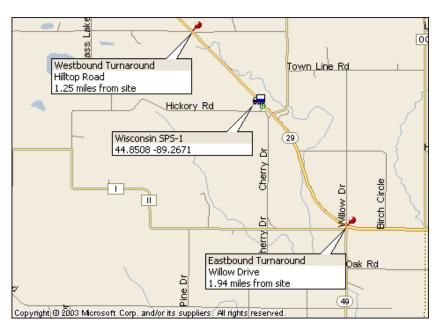


Figure 5-2 - Truck Route - 550100

Eastbound: 1.94 miles to Willow Drive
Westbound: 1.25 miles to Hilltop Road

6. Sheet 17 – Wisconsin (550100)

1.* ROUTE _	SR 29	MILEPOST _189.	8LTPP D	IRECTION - N S E \underline{W}
Neare	st SPS section	TION - Grade <u><1</u> on upstream of the site sor to nearest upstrear	0219	
3.* LANE CO	ONFIGURA'	ΓΙΟΝ		
Lanes	in LTPP dir	ection <u>2</u>	Lane width	<u>12</u> ft
	<u>3 –</u> 4 –	physical barrier grass none	Shoulder -	1 – curb and gutter 2 – paved AC 3 – paved PCC 4 – unpaved 5 – none
Shoul	der width _	<u>8</u> ft		
4.* PAVEME	ENT TYPE	portland cement	concrete	
Date <u>05/20/08</u> Date	8 Photo <u>55</u> Photo	0100 Upstream 05 0100 Downstream E loop – bending	05_20_08_	
		ND/OR GRINDING ND/OR GRINDING ND/OR GRINDING		
distan Interse distan	ection/drivev ce575' ection/ <u>drivev</u> ce _125' (sir	CTIONS vay within 300 m upsi vay within 300 m downgle house driveway) ly used for turns or pa	nstream of senso	_
9. DRAINA	GE (Bending	g plate and load cell s	ystems only)	1 – Open to ground2 – Pipe to culvert3 – None
		ate <u>6</u> o flush fines from uno		

10. * CABINET LOCA	ATION	
Same side of ro	ad as LTPP lane Y / N Median Y / N Behind barrier	Y / <u>N</u>
Distance	e from edge of traveled lane30 ft	
	e from system36 ft	
TYPE	3M	
CABINET ACC	CESS controlled by LTPP / STATE / <u>JOINT</u> ?	
Contact	- name and phone numberJohn Williamson (608) 26	7-2939
	te - name and phone numberJane Oldenburg (608) 24	
	•	
11. * POWER		
Distance to cab	inet from drop7 ft Overhead / <u>underground</u> / so	olar / AC
in cabinet?	. –	
Service provide	er Phone number	
•		
12. * TELEPHONE		
Distance to cab	inet from drop7 ftOverhead / <u>underground</u>	/ cell?
	er Phone Number	
-		
13.* SYSTEM (softwa	are & version no.)-	
Computer conn	ection – RS232 / Parallel port / USB / Other	
•		
14. * TEST TRUCK T	URNAROUND time minutes DISTANCE	_ <u>6.5</u> mi
15. PHOTOS	FILENAME	
Power source	55 0100 Power Source 05 20 08.jpg	
Phone source	55_0100_Telephone_Source_05_20_08.jpg	
Cabinet exterior	_55_0100_Cabinet_Exterior_05_20_08.jpg	
Cabinet interior	55 0100 Cabinet Interior Front 05 20 08.jpg	
<u>-</u>	55 0100 Cabinet Interior Back 05 20 08.jpg	
Weight sensors	55 0100 Leading WIM Sensor 05 20 08.jpg	
_	55_0100_Trailing_WIM_Sensor_05_20_08.jpg	
Classification sensors		
Other sensors	55 0100 Leading Loop 05 20 08.jpg	
	55 0100 Trailing Loop 05 20 08.jpg	
DescriptionLoop Se	nsors	
Downstream direction	at sensors on LTPP lane	
55_0	100_Downstream_05_20_08_	_
Upstream direction at s	ensors on LTPP lane	
55_03	100 Upstream 05 20 08	

COMMENTS
GPS Coordinates: Latitude: 44° 51.029' and Longitude: -089 ⁰ 15.997'
Amenities:
Hatley – 3 miles west of site: BP gas, Subway restaurant
Wausau – 20 miles west of site: Various gas stations, hotels,
restaurants, Home Depot
COMPLETED BY Dean J. Wolf
COMILECTED DTDCAILJ. WOIL
PHONE (301) 210-5105 DATE COMPLETED 5/20/08

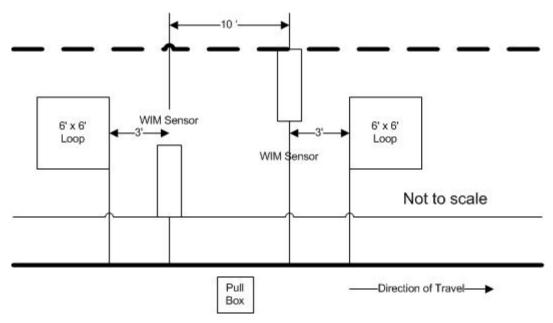


Figure 6-1 Equipment Layout - 550100

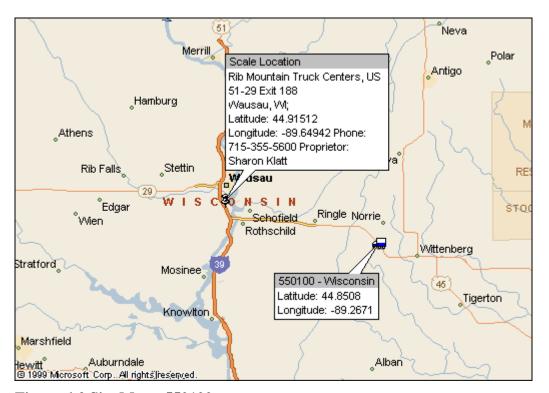


Figure 6-2 Site Map - 550100



Photo 1 - 55_0100_Upstream_05_20_08.jpg



Photo 2 - 55_0100_Downstream_05_20_08.jpg



Photo 3 - 55_0100_Power_Meter_05_20_08.jpg



Photo 4 - 55_0100_Telephone_Source_05_20_08.jpg



Photo 5 - 55_0100_Cabinet_Exterior_05_20_08.jpg



Photo 6 - 55_0100_Cabinet_Interior_Front_05_20_08.jpg



Photo 7 - 55_0100_Cabinet_Interior_Back_05_20_08.jpg



Photo 8 - 55_0100_Leading_WIM_Sensor_05_20_08.jpg



 $Photo\ 9\ \hbox{--}\ 55_0100_Trailing_WIM_Sensor_05_20_08.jpg$

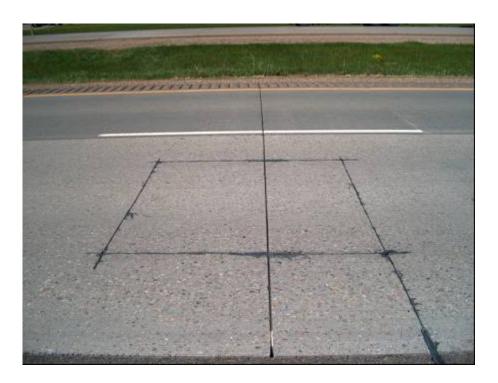


Photo 10 - 55_0100_Leading_loop_05_20_08.jpg



Photo 11 - 55_0100_Trailing_Loop_05_20_08.jpg

SHEET 18	STATE CODE	[55]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>05/20/2</u>	008

1.	DA	ATA PROCESSING –
	a.	State only LTPP read only LTPP download
	b.	LTPP download and copy to state Data Review –
		 State per LTPP guidelines State − Weekly Twice a Month Monthly Quarterly LTPP
	c.	Data submission – State – Weekly Twice a month Monthly Quarterly LTPP
2.	EQ	QUIPMENT –
	a.	Purchase – State LTPP
	b.	Installation − ☐ Included with purchase ☐ Separate contract by State ☐ State personnel ☐ LTPP contract
	c.	Maintenance – Contract with purchase – Expiration Date _5 years from installation_ Separate contract LTPP – Expiration Date Separate contract State – Expiration Date State personnel
	d.	Calibration – Vendor State LTPP
	e.	Manuals and software control − ☐ State ☐ LTPP
	f.	Power − i. Type − ☐ Overhead ☐ Underground ☐ Solar ii. Payment − ☐ State ☐ LTPP ☐ N/A

SHEET 18	STATE CODE	[55]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>05/20/200</u>	<u> </u>

	g.	Communication –
		i. Type − ii. Payment −
3.	PA	AVEMENT –
	a.	Type – Nortland Concrete Cement Asphalt Concrete
	b.	Allowable rehabilitation activities – Always new Replacement as needed Grinding and maintenance as needed Maintenance only No remediation
	c.	Profiling Site Markings – Permanent Temporary
4.	ON a.	N SITE ACTIVITIES – WIM Validation Check - advance notice required <u>2</u> ☐ days ☐ weeks
	b.	Notice for straightedge and grinding check2
		ii. Accept grinding − ☐ State ☐ LTPP
	c.	Authorization to calibrate site – State only LTPP
	d.	Calibration Routine – LTPP – Semi-annually Annually State per LTPP protocol – Semi-annually Annually State other –

SHEET 18	STATE CODE	[55]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>05/202008</u>	

	e.		vehicles Trucks –			
		i.	1st – <u>Air suspension 3S2</u>	State	X LTPP	
			2nd – <u>3S2 different weigh</u>		State	X LTPP
			3rd –	State	LTPP	
			4th –	State	LTPP	
		ii.	Loads –	State State	\times LTPP	
		iii.	Drivers –	State State	\boxtimes LTPP	
	f.	Contra	actor(s) with prior successful expe	erience in WIM	I calibration in	state:
		<u>IRD</u>	-			
	g.	Acces	s to cabinet			
		i.	Personnel Access –			
			State only			
			∐ Joint ☐ LTPP			
			_			
		ii.	Physical Access –			
	1.	Ctoto "		□v _{aa} ⊠na		
	h.	-	personnel required on site –	☐Yes ⊠No		
	i.	Traffic	c Control Required –	☐Yes ⊠No	•	
	j.	Enforc	cement Coordination Required –	☐Yes ⊠No	•	
5.	SI	ΓE SPE	CIFIC CONDITIONS –			
	a.	Funds	and accountability –			
	b.	Repor	ts			
	c.	Other				
	d.	Specia	al Conditions –			
6.	CC	NTAC	CTS –			
	a.	Equip	ment (operational status, access, e	etc.) –		
			Name: Roy Czinku	Phor	ne: <u>(306) 653-66</u>	<u>527</u>
			Agency: IRD			

SHEET 18	STATE CODE	[55]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID [<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>05/20/2008</u>	

b.	Maintenance (equipment) –	
	Name: Roy Czinku	Phone: (306) 653-6627
	Agency: <u>IRD</u>	
c.	Data Processing and Pre-Visit Data –	
	Name: Roy Czinku	Phone:(306) 653-6627
	Agency: IRD	
d.	Construction schedule and verification -	_
	Name:	Phone:
	Agency:	
e.	Test Vehicles (trucks, loads, drivers) –	
	Name: Greg Guite	Phone: 715-849-4000
	Agency: Elite Carriers, LLO	<u> </u>
f.	Traffic Control –	
	Name:	Phone:
	Agency:	
g.	Enforcement Coordination –	
_	Name:	Phone:
	Agency:	
h.	Nearest Static Scale	
	Name: Rib Mountain Travel	Location: US 51/SR 29 (Exit 188)
	<u>Center</u>	
	Phone: 713-359-8728	

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[55]
*SHRP SECTION ID	[0100]

SITE CALIBRATION INFORMATION

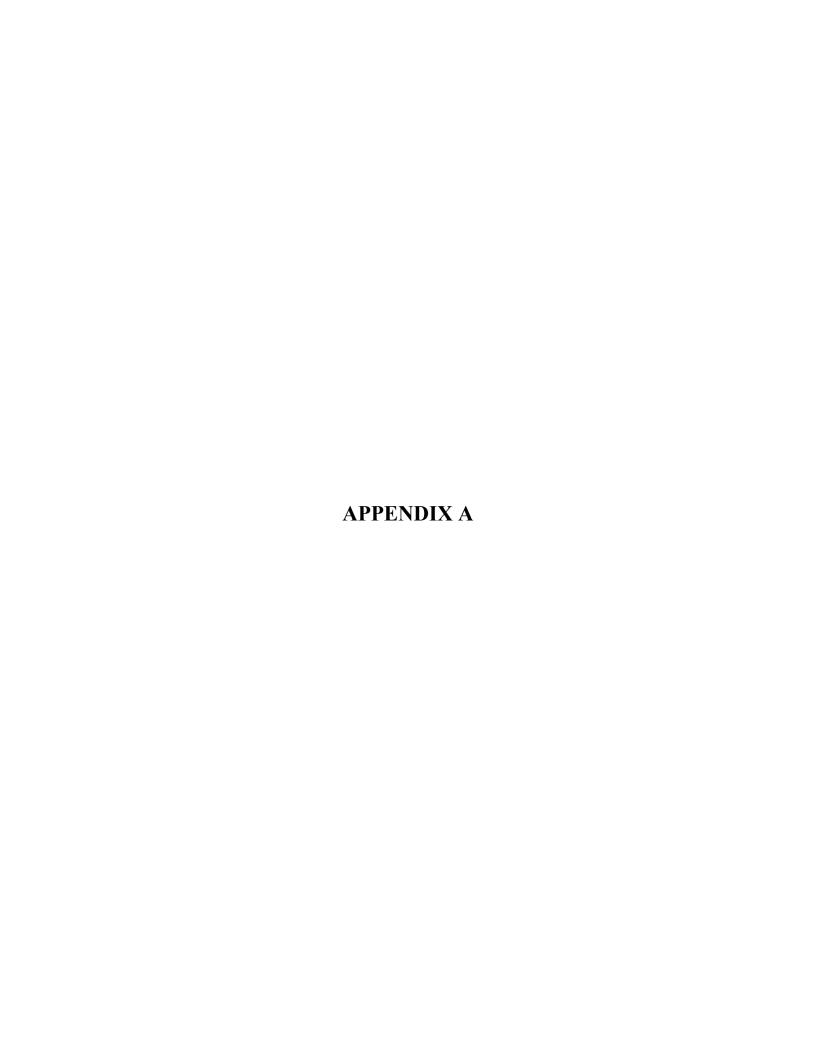
1. *	DATE OF CALIBRATION (MONTH/DAY/YEAR) [05/2	0/08]
2. *	TYPE OF EQUIPMENT CALIBRATED WIM	CLASSIFIER _X_BOTH
- -	REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION X OTHER (SPECIFY) LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
- - -	SENSORS INSTALLED IN LTPP LANE AT THIS SITE (CH_BARE ROUND PIEZO CERAMIC BARE FI_CHANNELIZED ROUND PIEZO LOAD CI_CHANNELIZED FLAT PIEZO X INDUCT_OTHER (SPECIFY)	ECK ALL THAT APPLY): AT PIEZO X BENDING PLATES ELLS QUARTZ PIEZO ANCE LOOPS CAPACITANCE PADS
5. E	EQUIPMENT MANUFACTURER IRD/ PAT Traffic	
	WIM SYSTEM CALIBRAT	ION SPECIFICS**
6.**(CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N)	X TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED AS MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW 3.2 DYNAMIC AND STATIC SINGLE AXLES 4.7 DYNAMIC AND STATIC DOUBLE AXLES 2.9	STANDARD DEVIATION 3.6
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATIO	N WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH) 55	60 65
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW	SPEED)3286, 3114
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N) _ IF YES, LIST AND DEFINE AUTO-CALIBRATI	
	CLASSIFIER TEST S	PECIFICS***
12.**	* METHOD FOR COLLECTING INDEPENDENT VOLUM VIDEO _X_ MANUAL	E MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIME X NUMBER OF TRUCKS
14.	*** FHWA CLASS 8 1 FHWA	A CLASS _515 A CLASS A CLASS
	*** PERCENT "UNCLASSIFIED" VEHICLES: <u>1.7</u>	A CLASS
	SON LEADING CALIBRATION EFFORT: <u>Dean J. Wolf, N</u> NTACT INFORMATION: <u>301-210-5105</u>	<u>ИАСТЕС</u> rev. November 9, 1999

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[55]
*SHRP SECTION ID	[0100]

SITE CALIBRATION INFORMATION

1. *	* DATE OF CALIBRATION (MONTH/DAY/YEAR) [5/21	/2008]
2. *	* TYPE OF EQUIPMENT CALIBRATED WIM	CLASSIFIER _X_ BOTH
- -	REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION X OTHER (SPECIFY) LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
- -	SENSORS INSTALLED IN LTPP LANE AT THIS SITE (CHBARE ROUND PIEZO CERAMICBARE FLCHANNELIZED ROUND PIEZOLOAD CHANNELIZED FLAT PIEZOX INDUCTOTHER (SPECIFY)	ECK ALL THAT APPLY): AT PIEZO _X_ BENDING PLATES ELLS QUARTZ PIEZO ANCE LOOPS CAPACITANCE PADS
5. E	EQUIPMENT MANUFACTURER IRD/ PAT Traffic	
	WIM SYSTEM CALIBRAT	ION SPECIFICS**
6.**0	CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N)	X TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED AS MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW 0.2 DYNAMIC AND STATIC SINGLE AXLES 0.8 DYNAMIC AND STATIC DOUBLE AXLES 0.2	STANDARD DEVIATION1.1 STANDARD DEVIATION1.5
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATIO	N WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)55	
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW	SPEED) <u>3386, 3210</u>
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N) IF YES, LIST AND DEFINE AUTO-CALIBRATION	
	CLASSIFIER TEST SE	PECIFICS***
12.**	** METHOD FOR COLLECTING INDEPENDENT VOLUMI VIDEOX_ MANUAL	E MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIME X NUMBER OF TRUCKS
14.	*** FHWA CLASS 8 <u>50</u> FHWA FHWA	ASSIFICATION: A CLASS _5
	*** PERCENT "UNCLASSIFIED" VEHICLES: <u>0.8</u>	CLASS
	RSON LEADING CALIBRATION EFFORT: <u>Dean J. Wolf, N</u> NTACT INFORMATION: <u>301-210-5105</u>	ACTEC rev. November 9, 1999



		PP Traffic Data	* SPS PROJECT ID	0100
Rev. 08/		ON TEST TRUCK #_1	* DATE	05/20/08
				trade 711 trade 53 4746
PART	1.		COAT	ticle 53 474A
1.* FH	WA Class^	2.* Number of Axles	5 Number of w	eight days ²
AXLE	S - units - (Îb) / 10	Os lbs / kg		
GEON	1ETRY			
8 a) * 1	Tractor Cab Style -	Cab Over Engine / Convention	nat b) * Sleeper Cab?	Þ/N
9. a) *	Make: Knweith	b) * Model:	***************************************	
10.* Tı	railer Load Distribu	tion Description:		
ţ	ills of pros			ANALOMA ANA
<u></u>				

12.* Ax	xle Spacing – units	m / feet and inches / feet B to C	C to D 3644 E to F	
13. *Ki	ngpin Offset From	Axle B (units) + \ (+ is t	to the rear)	
SUSPE	ENSION			
Axle	14. Tire Size	15.* Suspension Description	n (leaf, air, no. of leaves, taper or	flat leaf. etc.)
A	75 (22,5			
В	756225			
C	75 022.5	5		
D	<u> 15021.5</u>			
E	<u> 150225</u>			
F	***************************************			
64200700	022_SPSWIM_TO_26	_55_2.108_0100_Sheet_19_axle_sc	ales truck 1.doc	The second of th

* STATE_CODE

5 5

Sheet 19

Sheet 19	* STATE_CODE	5_5_
LTPP Traffic Data	* SPS PROJECT ID	_0_1_0_0_
*CALIBRATION TEST TRUCK # 1	* DATE	05/20/08
Rev. 08/31/01		

PART II

Day 1

*c) Post Test Loaded Weight

*d) Difference Post Test – Pre-test

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	12020	17140	171160	15360	15360		77060
2	12020	17160	17160	15360	15360		77060
3	1						
Average	12020	17100	17160	15360	15360		77060

Table 6. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11840	17090	17090	15 330	15330		76680
2	11850	17090	17090	15340	15340		76680
3							
Average	11830	17090	17090	15335	15375		76680

Measured By 1	Verified By	MZ	_Weight date _	5 20 03
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		Sheet 19		* 9	STATE CODE		5_5_
		TPP Traffic Dat	~*************************************		SPS PROJECT II)	010
0.0 (2.1 (2	**************************************	TION TEST TR	UCK # 1	* J	DATE		5/21/2008
Rev. 08/31/0	' I						
				Day 2			
7.2	*b) Average	e Pre-Test Lo	aded weight	7766			
	,	st Loaded Wo	_	77380			
	*d) Differer	nce Post Test	– Pre-test	2 8 (
Table 5.2.	Raw data – A	xle scales – pr	e-test				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	12400	17300	17300	15330	15330		77660
2	12380	17310	เารเอ	15330	15330		77668
3							
Average	12390	17305	17305	15330	IS 330		77660
Table 6.2.	Raw data – Az	kle scales –					
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1						and the same of th	
2							
3							
Average							
Гable 7.2 F	Raw data – Ax	le scales – po:	st-test				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
	12240	17250	17 250	15320	15320		77360
2	12260	17230	17230	15330	(5330		77360
3							
	······································			riikit (jili metala mineri menerum manana ananggaya yaya yaya	PARTAMETRICAL PROPERTY CONTROL OF THE PARTAMETRICAL PROPERTY CONTROL O		

17240

17240

15325

15325

Verified By Weight date 5-2,-08

773 80

12250

Average

WALE AND W	PP Traffic Data	* SPS PROJECT ID	0_1_0
	TON TEST TRUCK # 2	* DATE	
Rev. 08/31/01		Ditch	ma 750
PART I.		1. A. Tela	12W 53 445
1.* FHWA Class	2.* Number of Axles	5 Number	of weight days 2
.a01/79		1 (Gillioti (or weight days
AXLES - units - (bs)/10	00s lbs / kg		
GEOMETRY			
3 a) * Tractor Cab Style -	Cab Over Engine / Conventiona	b) * Sleeper Cab?	Ý) N
. a) * Make: <u>'FERWORTH</u>	b) * Model:		
10.* Trailer Load Distribu	tion Description:		
Papa lolls			weather the state of the state

1. a) Tractor Tare Weigh	t (units):		
	t (units): t (units):		
b). Trailer Tare Weigh	t (units):	**************************************	
b). Trailer Tare Weigh		**************************************	
b). Trailer Tare Weigh2.* Axle Spacing – units	t (units):	nd tenths	
b). Trailer Tare Weigh2.* Axle Spacing – units	t (units): m / feet and inches / feet and B to C 4.3	nd tenths C to D 32.8	
b). Trailer Tare Weight 2.* Axle Spacing – units A to B	t (units): m / feet and inches / feet and B to C	nd tenths	
b). Trailer Tare Weight 2.* Axle Spacing — units A to B	t (units): m / feet and inches / feet and B to C 4.3	nd tenths C to D 32.8	
b). Trailer Tare Weight 2.* Axle Spacing — units A to B Wheelbase (measurement)	m / feet and inches / feet and B to C	C to D 32 & E to F Computed 58.3	
b). Trailer Tare Weight 2.* Axle Spacing — units A to B Wheelbase (measurement)	m / feet and inches / feet and B to C 4.3 D to E 4.1 red A to last) 4.1.	C to D 32 & E to F	
b). Trailer Tare Weight 2.* Axle Spacing – units A to B Wheelbase (measur 3. *Kingpin Offset From	m / feet and inches / feet and B to C 4.3 D to E 4.1 red A to last) 4.1.	C to D 32.8 E to F Computed 58.3	
b). Trailer Tare Weight 2.* Axle Spacing – units A to B Wheelbase (measur 3. *Kingpin Offset From	m / feet and inches / feet and B to C 4.3 D to E 4.1 red A to last) 4.1.	C to D 32.8 E to F Computed 58.3	
b). Trailer Tare Weight 2.* Axle Spacing – units A to B Wheelbase (measur 3. *Kingpin Offset From	m / feet and inches / feet and B to C 4.3 D to E 4.1 red A to last) 4.1.	C to D 32 & E to F Computed 58.3 the rear)	
b). Trailer Tare Weight 2.* Axle Spacing — units A to B Wheelbase (measur 3. *Kingpin Offset From USPENSION	m / feet and inches / feet and B to C	C to D 32.8 E to F Computed 58.3 the rear)	er or flat leaf, etc.)
b). Trailer Tare Weight 2.* Axle Spacing — units A to B Wheelbase (measur 3. *Kingpin Offset From USPENSION Axle 14. Tire Size	m / feet and inches / feet and B to C 4.3 D to E 4.1 Ted A to last) 4.1 Axle B (units) + 1. (+ is to	C to D 32 & E to F Computed 58.3 the rear)	er or flat leaf, etc.)
b). Trailer Tare Weight 2.* Axle Spacing — units A to B	m / feet and inches / feet and B to C 4.3 D to E 4.1 Ted A to last) 4.1 Axle B (units) 41. (+ is to 15.* Suspension Description (C to D 32.8 E to F Computed 58.3 the rear)	er or flat leaf, etc.)
b). Trailer Tare Weight 2.* Axle Spacing — units A to B	m / feet and inches / feet and B to C 4.3 D to E 4.1 red A to last) 4.1 Axle B (units) + 1. (+ is to 15.* Suspension Description (C to D 32 & E to F Computed 58.3 the rear) Cleaf, air, no. of leaves, tape	er or flat leaf, etc.)
b). Trailer Tare Weight 2.* Axle Spacing — units A to B Wheelbase (measur 3. *Kingpin Offset From SUSPENSION Axle 14. Tire Size A	m / feet and inches / feet and B to C 4.3 D to E 4.1 Ted A to last) 4.1 Axle B (units) 41. (+ is to 4.4 Axle Axle Axle Axle Axle Axle Axle Axle	C to D 32.8 E to F Computed 58.3 the rear)	er or flat leaf, etc.)
b). Trailer Tare Weight 2.* Axle Spacing — units A to B	m / feet and inches / feet and B to C 4.3 D to E 4.1 Ted A to last) 4.1 Axle B (units) 41. (+ is to 4.4 Axle Axle Axle Axle Axle Axle Axle Axle	C to D 32 & E to F Computed 58.3 the rear) Cleaf, air, no. of leaves, tape	er or flat leaf, etc.)

* STATE_CODE

Sheet 19

	Sheet 19	* STATE_CODE	5_5_
	LTPP Traffic Data	* SPS PROJECT ID	0 1 0 0
	*CALIBRATION TEST TRUCK #_2_	* DATE	05/20/00
ev. 08/3	1/01		
	Da	ay 2	
.2	Da*b) Average Pre-Test Loaded weight	ay 2 65300	
7.2			

Table 5.2. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	1136 D	151000	15170	13310	13310		68332
2	11360	12160	15160	13300	13300		68280
3							
Average	11360	15165	15165	13305	13305		68300

Table 6.2. Raw data - Axle scales -

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average				THE PROPERTY OF THE PROPERTY O	A STATE OF THE STA	***************************************	And the state of t

Table 7.2 Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11160	15110	15110	13310	13310		68000
2	11140	15110	15110	13310	13310		67980
3							
Average	11150	15110	12110	13310	13310		67990

Measured By	Verified By	Weight date 5 /20 (08
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Sheet 19	* STATE_CODE	_5_5_
LTPP Traffic Data	* SPS PROJECT ID	_0_1_0_
*CALIBRATION TEST TRUCK # 2	* DATE	
Day 2		

*b) Average Pre-Test Loaded weight
*c) Post Test Loaded Weight
*d) Difference Post Test – Pre-test
*d) Difference Post Test – Pre-test

Table 5.3. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11580	15200	15200	13290	13290		68920
2	11560	15210	15210	13300	13300		685% 0
3							
Average	11570	15205	15205	13295	13295		68570

Table 6.3. Raw data - Axle scales -

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
. 							
2							
3							
Average					NAME OF TAXABLE PARTY O	44.000 AMARIAN AND AND AND AND AND AND AND AND AND A	

Table 7.3. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11400	15160	15160	13300	13300		68320
2	11400	15160	15160	13290	13290		68300
3							
Average	11400	15160	15160	13295	13295	CONTROL OF THE PROPERTY OF THE	68310

Measured By	Verified By _	V02-	Weight date <u>5-71-08</u>
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Sheet 20	* STATE_CODE	5 5
LTPP Traffic Data	*SPS PROJECT_ID	0 1 0 0
Speed and Classification Checks * \ of* \	* DATE	05/20/2008

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
65	9	738	GU	9	70	9	848	ET.	
76	9	つり	68	9	6 3	9	451	63	9
40	9	748	340	9	66	9	852	66	9
67	ジ	つり	66	5	64	9	853	63	9
64	5	752	63	4	58	8	858	57	8
64)	756	64	つ	68	9	859	68	9
62	9	758	62	9	63	9	965	63	9
64	9	767	G (3	\$ 9	60	9	870	60	9
7=	9	77/	つ1	9	67	9	87]	6)	9
61	9	778	86	9	65	9	87.2	65	9
40	5	780	40	5	67 ·	6	879	67	4
68	4	78)	66	44 5	63	6	883	63	6
62	9	787	G)	9	62	9	884	63	9
5 8	9	784	<i>5</i> 8	9	65	10	894	65	10
38	5	786	36	5	62	8	<i>49</i> 9	62	8
71	9	フ8フ	69	9	64	9	96/	GH	9
6)	5	794	6 i	5	63	8	92)	63	Ŷ
68	9	7 9 5	68	9	68	6	923	68	6
69	8	799	69	8	64	2	934	64	
<u> </u>	9	806	64	2	60	8	939	60	8
68	9	810	47	9	65	9	941	65	9
62	9	82-0	61	69	67	9	943	65	9
69	9	821	69	9	64	9	949	63	9
65	9	842	64	Í	70	9	951	フロ	9
62	9	846	662	9	つっ	9	955	69	9

Recorded by AHM Direction W Lane Time from 1:50PM to 2:43PM 6420070022 SPSWIM_TO_26_55_2.108_0100_Pre-Validation_Sheet_20.doc

Sheet 20	* STATE_CODE	_5_5_
LTPP Traffic Data	*SPS PROJECT_ID	0 1 0 0
Speed and Classification Checks * 2 of* 2	* DATE <u>5/2</u>	1.08

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
(4	g	759	65	3	65	9	108)	65	9
6165	4 5	960	54	5	67	9	1094	67	9
45	4	961	65	5	68	2	/40 Y	68	9
67	9	966	66	9	64	5	1105	64	5
68	5	968	69	5	60	8	1112	60	98
67	9	975	67	9	52	6	1130	51	6
67	9	979	67	9	64	9	1133	64	9
63	9	987	64	9	72	9	1147	つ/	9
68	9	996	68	9	lobo	8	1160	66	5
68	9	1004	67	9	62	9	1161	62	9
60	9	1005	61	9	455	9	1162	60	9
65	9	1011	6)	9	64	Ì	1163	64	9
64	2	1012	66	9	68	15	1165	68	9
64	2	1015	65	9	67	10	1166	67	9/0
65	9	1018	65	9	65	9	1174	66	9
64	9	(524	64	9	67	5	1175	67	5
GE'	9	1922	62	9	68	9	/182	69	9
65	9	1030	65	9	うら	9	1184	69	9
62	9	<i>(</i> 631	62	9	54	9	112)	54	9
6)	2	(637	66	9	68	9	1193	67	9
67	9	1040	67	9	65	9	1201	64	9
6)	gumen"	1052	67	5	SH	9	/203	52	9
67	9	1053	67	9	66	6	1200	6066	6
65	8	1059	65	8	64	9	1213	\$65	9
64	9	107/	62	T	64	5	1218	64	5

Recorded by MTPLY Direction W/ Lane Time from 2:43 to 346 m
6420070022 SPSWIM_TO 26_55_2.108_0100 Pre-Validation_Sheet_20.doc

Sheet 20		* STATE_CODE	5 5
LTPP Traffic Data		*SPS PROJECT_ID	0 1 0 0
Speed and Classification Checks *	/_of*_ <u>Q</u>	* DATE	5/21/08

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
68	9	3739	68	9	64	9	3845	64	9
68	9	3740	(ŧ	9	65	9	3848	65	9
64	2	3744	(4	9	67	9	3851	66	9
66	9	3749	66	ğ	65	9	3856	65	9
65	9	375)	65	3	60	6	3860	59	6
75	9	3753	75	9	68	9	3862	69	9
67	g	3768	67	9	66	9	3863	66	9
68	9	3774	68	9	45	5	3869	65	5
67	6	3780	67	6	67	9	3870	67	9
68	522	3786	69	Classy IA	64	9	3987	64	9
65	9	3787	63	9	65	9	3850	63	9
59	Í	3801	(Ø5	9	(45	9	389)	65	9
63	9	3864	62		60	5	3895	61	5
65	2	3807	64	9	65	9	38 9 8	65	9
55	5	3808	56	Live San	65	5	3901	66	5
68	9	38/2_	68	9	70	9	322	69	9
63	9	3813	<i>4</i> 3	9	65	2	3507	66	7
65	9	3814	66	9	64	9	3911	65	9
64	9	3818	64	9	63	9	3918	64	9
62	8	3824	62	8	64	2	3927	64	9
70	2	3827	69	9	64	9	3,928	64	9
68	2	3828	68	9	70	9	3930	70	9
62	5	3835	61	5	48	9	3933	69	9
63	8	3836	63	8	63	8	3935	63	8
63	5	3844	63	9	65	9	3936	45	9

Recorded by MARIC Direction W Lane / Time from to //503AM to //503AM 6420070022 SPSWIM TO 26_55_2.108_0100_Post-Validation_Sheet_20.doc

Sheet 20	* STATE_CODE	5 5
LTPP Traffic Data	*SPS PROJECT_ID	0_1_0_0
Speed and Classification Checks * 2 of* 2	* DATE 5 / 2)	108

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
G5	9	3945	45	ğ	G5	9	4037	65	9
(5	9	3946	45	9	64	8	4048	65	8
74	9	3950	6 74	9	65	5	4040	65	5
62	9	3954	64	9	62	9	4050	61	9
68	13	3956	68	13	7%	9	4657	71	9
67	5	3964	66	5	60	7	4559	61	フ
65	5	3,965	64	5	70	5	4661	75	5
65	5	3966	64		64	6 (4062	4	6
70	ダ	3970	<i>49</i>	9	65	9	4067	66	9
67	9	3074	68	2	70	6	4085	フヮ	6
66	9	3979	66	9	69	9	4086	70	9
65	9	3980	65	9	<u>55</u>	10	4-93	65	10
56	9	3987	5 5	9	<u>5</u>	10	4094	65	10
57	9	3988	60	9	Ç., 6	9	4099	66	9
52	B	3995	52		59	9	4004	61	9
45	9	3999	65	Ğ	つシ	. 9	4109	200 772	9
69	9	4000	63	2	62	9	4113	6562	9
67	9	4004	47	9	68	9	4116	69	2
65	Secretary Secretary	4065	G5		65	9	4119	64	9
69	9	4-13	68	<i>-9</i>	98 955	8	4120	4 55	5
64	9	4022	64	g	65	2	4127	65	9
66	9	4024	66	9	Ç3.7		41238	69	9
64	9	4025	65	9	66	9	4135	66	9
68	9	4035	68	9	64	67	4137	63	7
65	9	435	65	9	65	Ø	4141	4 765	9

Recorded by MARK Direction W Lane / Time from 1/66 Mto 11:57 AM
6420070022 SPSWIM_TO_26_55_2.108_0100_Post-Validation_Sheet_20.doc

LTPP Traffic Data	* STATE CODE *SPS PROJECT ID	0 1 0 0
WIM System Test Truck Records 1 of 3	* DATE 0 5	3/20/2008

E-F space																
D-E space	0 5		÷	arrows.	Ť	5	7.		.5.		· instant	ට ජ	Ī			3
C-D space	32.7	36.5	2,00	7.	32.8	34.5	22.7	36.6	32.8	r.	32.6	3.	% %	in the second	32.9	34.5
B-C space	7,		<u>بر</u>	7.7	ry T	<i>;</i>	7	To the second	7	Ī	7	es T	in in		7	7
A-B space	ļ	,	Ċ	grander grander	 	<u></u>		~	Š	Ë	Ľ.	0 <u>C</u>	<u></u>	Ē.	,	بر <u>ت</u>
GWV	68.0	<u>න</u> 2	9 0	į	73.2	78. 6	9	\$ \$	12.0	7.2	Ö	300	10.3	<u>2</u>	734	74.3
Axle F weight																
Axle E weight.	1.3	1.7	£4,-9	7.6/	121	# <u>U</u>	4.3/	0.3/ 18.0	6.8/ 7.3	0.1/	1.7	5°C 0°9	7.4 159	6.3/	7.0/	72
Axle D weight.	6.5/L	8.7 7.4	5.7J 4	83/L9		<u>ا</u> ئۇ	-	\$.4/ 7.3	59/21	8.21 16.8	6.3/	T. C.	9/3/ 12/2	24/2	, o, C,	100
Axle C weight.	7.7	47/84	15/	200	050 C	7	S.C.	2.8/	ا م م	974	1.2	8,9 G	7.7	9.00 V.	09 	رن ان ان
Axle B weight.	6.9/	to.of	7.4/ 8.0	-2. -2. -2.	7	9.51	63 85 5	10.11 10.01	1.9/	4.5/8.2	675)	9.0	7. <i>3]</i> }&.4	5.7/ 18.9	7.6/ 18.2	9.0
Axte A weight.	6.0/	1.9	ν. γ.	23	7.3	15:3	7.7	k7 [.0	2.3	33	3	7-7	6.1 5.8	7	7	5.9
Speed	ß	5.5	\$	\^ _3	09	乙	5	5 8	5	J	3	Ş	K	5	\$	5)
Record No.	165	29. S.B.	5	<u>1</u> 7	200	8 22	751	260	(~)	<u>5</u>	2,5	317	23. 23.	353	2	379
Time	11:15	07.11	11:23	50 27 1		25:	04.0	4.1	9 =	2	23	1.55	50.21	30:21	2:2	91:21
Pass		, questo	Н	И	, C	~	Ţ	**	\n	5			("	r-	حتي	○
Truck	7	,120 -226 1 ²⁵	g ^{r, s} od	recover	И	:	N	المشميرين	اسا		t-3	4,13,214.HP	۲,	, paga mar	d	
Radar Speed	ß	9	7	<u>ئ</u>	0	あ	(V)	20	ঠি	\	l,	<u></u>	S	ى ئى	0	5
Pvmt temp	73	و بر	76.5	V.	<u></u>	10.	2	0	5	5	£	25	S		22	77.7

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Sheet 21	* STATE CODE	5.5
LTPP Traffic Data	*SPS PROJECT_ID	0 1 0 0
WIM System Test Truck Records 2 of 3	* DATE	8002/02/50

E-F space																
D-E space	Ť	0,7	Supar	<u>.</u>	- Crus		ī	أسيد	٥ خ			تر تر	ير. ن	0 ÷	- Nigorosa - Nigorosa - Nigorosa	
Space Space	32.7	36.4	32.8	36.5	1:28	36.3	22,1	36.5	22.7	7. 5.	1,25	かれ	928	ž, V	72.7	\$6.3
B-C space	7,7	7	N.	7	ر ا	I,	C,		4, 3	7, 20	<u> </u>	7	i, V	3	z,	~ ~
A-B space	<u> </u>	о <u>С</u>	<u>C</u>		, ser	Ē	Ç	-	(1100)	<u>Ler</u>	1.7		o C	C		0.5
GW G	15	18.3	7. CB. 5	9000	0. T L	77	9789	6. C.	¥.73	178	なれ	6.3	6	E &	ر دور د	62.6
Axle F weight																
Axle E weight.	7.6	8.1/ 7.3	2.7/2	6.3/	77	7%/ 714	0.7)x.3		53	4.U.3	2. 2. 2.			<u> </u>	77.0	47) 3-3
Axle D weight.	18/ 7.1	6.4 7.2	S.81		73	gof As	4.9. (Jule	2.7	73	9.4		- C	2,7,3	82/ 134	#4J03	9,7
Axle C weight.	9-5-6 -18-1	Delta Delta	7.7	9.5/ 8.4	F	13/83	14/ 17.6	0.8/ 0.8/	T.	9.8/ 18.5	900	1.00	50 Fr.	8.3/	1.57	92
Axle B weight.	1.3	92/ 12.5	7.3	9.8/	7.5%	7.9 1.3		1000 1000 1000 1000 1000 1000 1000 100	7.3		Z. Z	8,5 K	7.1 8.4	83/ 14.5	1.9/ 18.1	3.
Axle A weight.	5.8/	6.3/	S.e. C.S.	, ,) - -	# 7 % S	5.6/	27	10.0		, y , y , y , y , y , y , y , y , y , y	0.9	5.4	6.3/	2. X 7. 2.	\$ 6.5 \$ 4.7
W/IM Speed	2	Z	2	E	S	Ţ	こ こ	j,	3	3	<u>بر</u>	Š	رع	3	52	0
Record No.	398	T	Ĩ	ž	760	3	7	ر د ک	00 Æ	7.73	9 5 6	<u>ē</u>	ာ ဗာ ဇာ	885	5	920
Time	3.3	(2:23	7.7	2.2	13:52	iv K	14.60 80	7 67	20° Z	9	<u>خ</u>	5	Ë	H2.H)	N. 30	14:32
Pass	2	2_	2	2	سنجوالفع فتحدوني	-gan-Pilage. -gan-piredit	7.7	d	643	6	<u> </u>		\S	2		حــ
Truck	7		N	an BOO (Harley)	7	.merit/H47		واستعبيت	ç4	, yearson to the same of the s	Ч	pyross.	N	,rakoi+	63	*>000000
Radar Speed	Š	67.) Ev	エン	سي) مر)	8	1-	7	<i>M</i>	×	ود	ر د	5	3	K	S	2
Pvmt temp	S	Ä	7	2	7 2	2.5	တ်	80	05 R_	وي م	\$5 \$2 \$	æ ~	35.5	ŝ	5	3

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Sheet 21	* STATE CODE	5.5
L TPP Traffic Data	*SPS PROJECT ID	0100
ste	* DATE	2/20/20/2

 	·· , · · · · · · · · · · · · · · · · ·	· · · · · · · · · · · · · · · · · · ·	·····	·,	·								
E-F space													
D-E space	-13 -13 -13 -13 -13 -13 -13 -13 -13 -13	+	2 3 3 1 1 1 1	9 2	o Ť	٥ ٣	1923-1976 1970-1976	,					
C-D space	32.5	F3%	8.25	Ę	72.7	\$3	32.7	36.4					
B-C space	7.7	<u> </u>	7	h~ -g	ユ	~ **	7 h	r,					
A-B space	Singer Bring	07.0	Ī	071		0,7) [
0.VW	73.5	75.8	5	7.32	ر د	Š	73.4	212					
Axle F weight													
Axle E weight.	4.97	800 17.0	F12/	8.7/ 7.8	2.5	0.5/ 18.0	5	7.5/					
Axle D weight.	7.76	Z S	52/3	1 1 2 1 1 2 2 1 1 2 2 1 2 2 1 2 2 2 2 2		8-71	200	75-1		:			
Axle C weight.	70.7	80	7.7	7°3/ 10'5	7.3	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	25	9/8.0	The contract of the contract o				
Axle B weight.		200	72/	9.3/	52	و. خ د)	88 2. 7.		_			
Axle A weight.	F:3/	5.3	- 4/5.8 - 4/5.8	63/60 9.1/8.6 9.0/2 81/74 -	5.5%	- 		12					
WIM Speed	ر 20	Ş	Ţ	75	<u>r</u>	3	τ ν α_	Š	The appear of the delication of the Control of the				
Record No.	255	55	525	2	L'O)	(025	弘) (0.5%	A Lamando				
Time	88:H	H. S	7.45 5.45	G E	ならな	IL SS)S:00	L.C.	i (e e e e e e e e e e e e e e e e e e e		a compared for force		
Pass			99	32	٢	2	2	2,0					
Truck	Ķ	لمتبهو	d	بيورون الم	N	(Samp)	Ŋ	· zon-Martinegaji					
Radar Speed	5	و و	\$	ß	S	2	Š.	Š					
Pvmt temp	5.3	5	\$ \$ \$	43,5	%.H.S	いま	5.50	89.5					

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Sheet 21	* STATE CODE	5.5
	*SPS PROJECT ID	0 1 0 0
WIM System Test Truck Records of	* DATE	8004/14/60

E-F space														
D-E space	7.7	1	٦. ٥.	7		1.4		٦	t, 0	****	3	7		
c-D space	32.8	7. ° 7	25	t. 92	7.25	25.5	32.8	76.4	32.7	N K	32.7	28.4		
B-C space	4.3	7	7.	7	, T	J	Ţ.	H.3	1 V	3	Ţ W	J		
A-B space	17.1	Š	<u></u>	Ĉ	<u> </u>	Ē	,	17.5	17.0	<u> </u>		C C		
GVW	5.13	76.00	6 % 50:3	r F	1.10 0.93	7.0	200	25	0.0 %3 3	X	2.8.	92 29 20		
Axle F weight														
Axle E weight.	5.L/ 7.2	7.7	27 27 27	1.5/ 17.6	6.2/6.5	627	(23/7)	5°C/0°8	6.87	7.	6-1/ h.3	2.7/ B		
Axie D weight.	15.3	4. C.	16.5	7.7.7.2	37	89/9 81/3 82h	J 1.7/2 61/1.1 6	8.c/	5.4	2.5	45.7 7.3	\$.5% F.77		
Axle C weight.	7.3/	3.c/ /4.o	4.2/ /h'l	1.00 1.00 1.00 1.00	7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7	5.9/	7.7/ 1.2	9.01. 891	1.3/1.6	7.3	7.5/	00 - 00		
Axle B weight.	7.17	8.3/ 18.6	18.	16.5	7.03	1.0/	2,0/	9.00 0.50	30	7.25	4. 93	4.7 8.4		
Axle A weight.	5.4	6.5/ 16.5	5.5/6.1	4.2/6.2	5.7/	6-3/ /b.1	99	6.3	0.9/	\$ 8 P	5.4	1.9/		·
Speed	8	さ	Ş	<i>۵</i>	9	J	S	ß	S	09	99	ħ9		
Record No.	3439	3740	34.79	35	3514	35.5	3546	3547	3543	3545	3635	3636		
Time	8:52	50.52	ತ ಕ	ة ض	و هن م	5	Ē	C. G	9.25	22%	F. 3-	なっ		
Pass	Marketon		2	Ν	Μ	m	کر,	3	V		و	ک		
Truck	7	معتمي	4	- Inches and	7		N		7	_{ph} later to a	L3	Madiffiles		
Radar Speed	10 10	2 2	0	なり	S	5 9	X	70	5	9	~3 ©	ろ		
Pvmt temp	5.25	\$2.5	53	S	22	χ. .,	22.5	5.58	53	\$	53.5	53.5		

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Recorded by Name 12 and 12 and

* STATE CODE 5 5	*SPS PROJECT ID 0 1 0 0	* DATE 25/21/2008
Sheet 21	L'TPP Traffic Data	WIM System Test Truck Records of 2.

F-F space																
D-E space	5 T	j	ĵ	<u>,</u>	7	<u> </u>	ブ	ر ح	**************************************	**************************************	Marie Ma	4.1	j	0. J		•
c-D space	32.6	252	72.7	2.5	32.7	かな	22.00	7.76	32.7	N A	1.12	36.4	37.8	36.3	32.7	7.5
B-C space	2,	3	7.7	٠, «\	7,	× 7	CV.	4.3	7,	j J	٦. ٧	エニ	دم ت	i vi	7	T
A-B space	17.0	C	0	5	Janes .	Č	<u></u>	C	0 0	S	Č	f ^{alle} les,	C	C O	C	Ē
GVW.	35	12 12	2,2	5.7	S	18.0	Ž	7 00	2.5	60 2 2	67 67	150 50	Ç.,	90	2	7.3
Axle F weight																
Axle E weight.	77	25/25	2	78/	77.3	7.9/	0.0% %7%	7:3/	7.4	1.4 1.7 1.7	-7~	2.78.5	٢		<u> </u>	2.4
Axle D weight.	5.8/	13 CO 00	2.4	ف خود	7.2/	3.7	200	777	7 4	12	0.E/20	8.2/.7	6.3/	- C	7	3
Axle C weight.	7.2 7.5	9.0/ 18.0		7.00	7.4	92/	714	9.6	7.7	7 (3)	7.1/1.8	73	15/	6.3/	TH 7.50	0.8 7.6
Axle B weight.	6.7/2	8.7/	2.3/	7	691	20		\$ 16/ 10/ 2.5	6-8/	90 20 20	676	000	7.01	200	1.3%	75.
Axle A weight.	5.41	r. 3	5.5/	,	5.1		15 15 15 15	4.3/	0,8 F. i.S	62	5.5/6.3	6.3	52.	6.3/	5.2	8.5/c. 1
WiM Speed	50	8	\$5	5	و. و	. <u>9</u>	S	ま	25	5	2	3	3	こ	<u>~</u>	C
Record No.	3443	38	77,54	3765	3743	7	3822	3823	52	78.58 53.58	30.66	3883	3923	7924	37.50	ZIG -
Time	77.5	2 H. To	0.50	0:10	97	တ ခ်	200	Gä	(6:35	16;3k	15.0	10:45	6:53	5.5	11:03	5
Pass	J	C	9-0	Charles	Ġ	Œ	0	2	Name and Associated Association of the Association	-	2	Ü	61/	in.	I	7
Truck	2	- tarectar	rs	ويجلكاتهس	ri	; paratury,	N	**************************************	7	- Proposition	rd	Marrores	Ŋ	N)-mail-propaga	, d	**************************************
Radar Speed	S	Z	9	79	23	3	7	χ ~	0	2	3	3	5 ,	53	ي م	
Pvmt temp	5	<u></u>	ج ا	7.6	S:S	S	3	3,000	(C)	5:2	C	c	Š	223	S	5,53

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	5.5	0 1 0 0	00/14/140000
	* STATE CODE	*SPS PROJECT ID	* DATE
The state of the s	Sheet 21	LTPP Traffic Data	WIM System Test Truck Records 2 of 2.

E-F space															
D-E space	· manga. · mangana	1	4		50		7,	<u></u>	0 /	0	- Homesey	5	J	J.	
C-D space	57.5	32.3	7 33	32.0	E K	87.75	t K	32.8	36.4	32.7	7.3	7.9	3.35	37.6	
B-C space	J.	5	た。	Z.	, 	×	<u> </u>	7,7	J J	ル ナ	3	7,	ž.	##. iv	
A-B space	5	Ľ.	Č	I'C	٥ <u>ت</u>	S	0,7		C'	Ċ.	1.7	Ē		<u> </u>	
@M®	25	3	7.3	5.30	25	و ئۇ	<u> </u>	0.8	E	69.5	3.5	5	78.2	5:5	
Axle F weight															
Axle E weight.	77.8	7"	8.0/ 70.3	63/2	7.9. J.C	6. C/	7,4		7.3/	3	7.16	5.	8.1/ 7.3	6.4	
Axte D weight.	30 12 12 12 12 13 13 14 15 15 15 15 15 15 15 15 15 15 15 15 15	6.5/1.3	57/0	7.16.8	7.7	e.s.	8:4 1.5	5.2	7.00 7.10 7.10 7.10	6.3 7.3	7.5/h.2	5	h. 2. 5. 5.	7.0.7	
Axle C weight.	30/	Ŧ,	927	7.4/	10 mg	2			0.8/ 8.8/	7.5/LS	8.9	7.3 h.3 %	9 9 00 00 00	7.6	
Axle B weight.	\$ 50 50 50	1.2/80	5	7.5	4.16.2	72	72.5	2	1.50 1.50 1.50 1.50 1.50 1.50 1.50 1.50	\$ 3/ /b. 4	25.7 25.00 3	73	F. 87 25	7 7 7	
Axle A weight	6.4	5.7/	6.5/	5.3 7.53	6.3	5.5/5.9	73/23	5.71	5:3/	5.4%		7. Z.	7	5.0%	
WIM	7	ود	25	\$	Zv ³	2	2	9	\$	ß	5	2	59	99	
Record No.	4245	25,25	<u> </u>	40,4	<u>5</u>	30 T	727	Ë	き	ž Ž	7 == == == == ==	5	Y22Y	UZZH	The state of the s
Time	2		W.35	25.31	4,17	3	55.3	8	[S]	S	\$0:21	10:27	<u>.</u>	T. C	
Pass	72	~		2	<u> </u>	<u></u>	<u>~</u>	o'e	and a second	<u>a</u>	2	9	N	ū	
Truck	.— Def	2	, mag waterwee	N	المستجدة المنتدر	7	- Mary Park	4		И	pydradada	(~)	meteorer	n	
Radar Speed	-3 9-	j.	2	办	S. S	50	2	Ŋ	Ž,	₩ W	2	5	S	Š	
Pvmt temp	S	~ る	r a	\$	35.5	3,	ç	50	00	ر ا	V	22	S	Š	and the second s

Recorded by Ohm

Checked by_

6420070022_SPSWIM_TO_26_55_2.108_0100_Post-Validation_Sheet_21.doc

Calibration Worksheet

Site: 550100

Calibration Iteration 1 Date 5-21-08

Beginning factors:

Speed Point (mph)	Name	Left Sensor	Right Sensor
Overall			
Front Axle			
Distance		372	
1-(50)	80 Kbr	3131	3302
2-(55)	88 koh	3211	3388
3-(60)	96 ligh	339Z	3579
4-(65)	104 kph	3114	3286
5-(70)	112 kph	3099	3269

Errors:

	Speed Point				
	1()	2 (55)	3 (60)	4 (65)	5()
F/A		+4,2	+7.9	- 0,3	
Tandem		+ 1.1	+6.5	1.7_	
GVW		+ 1.5	+6.7	-1.0	

Adjustments:

	Raise	Lower	Percentage
Overall	Service Constitution of the Constitution of th		
Front Axle	in record		
Speed Point 1			
Speed Point 2		Z	-1.5
Speed Point 3		\boxtimes	(, :7
Speed Point 4			+3.0 *
Speed Point 5		announg .	

+3.0% manual Calculation based on slant from 60 to 65 mph.

End factors:

Speed Point (mph)	Name	Left Sensor	Right Sensor 2/A
Overall	·		
Front Axle			
Distance		372	
1-(50)	80 Kph	3 \ 3 \	3302
2-(55)	88 Lph	3162	3336
3-(60)	96 kph	32LO 3164	3338
4-(65)	104 kph	3099 3210	3386
5-(70)	112 kph	3099	3269

64200 70022 SPSWIM TO 26 55 2 10% 0100 Calibration Iteration | Worksheet

TEST VEHICLE PHOTOGRAPHS FOR SPS WIM VALIDATION

May 20, 2008

STATE: Wisconsin

SHRP ID: 550100

Photo 1 55_0100_Truck_1_Tractor_05_20_08.jpg	2
Photo 2 55_0100_Truck_1_Trailer_05_20_08.jpg	
Photo 3 55_0100_Truck_1_Suspension_1_05_20_08.jpg	
Photo 4 55_0100_Truck_1_Suspension_2_05_20_08.jpg	
Photo 5 55_0100_Truck_1_Suspension_3_05_20_08.jpg	
Photo 6 55_0100_Truck_2_Tractor_05_20_08.jpg	
Photo 7 55_0100_Truck_2_Trailer_05_20_08.jpg	
Photo 8 55_0100_Truck_2_Suspension_1_05_20_08.jpg	
Photo 9 55_0100_Truck_2_Suspension_2_05_20_08.jpg	
Photo 10 55_0100_Truck_2_Suspension_3_05_20_08.jpg	



Photo 1 55_0100_Truck_1_Tractor_05_20_08.jpg



Photo 2 55_0100_Truck_1_Trailer_05_20_08.jpg



Photo 3 55_0100_Truck_1_Suspension_1_05_20_08.jpg



Photo 4 55_0100_Truck_1_Suspension_2_05_20_08.jpg



Photo 5 55_0100_Truck_1_Suspension_3_05_20_08.jpg



Photo 6 55_0100_Truck_2_Tractor_05_20_08.jpg



Photo 7 55_0100_Truck_2_Trailer_05_20_08.jpg



Photo 8 55_0100_Truck_2_Suspension_1_05_20_08.jpg



Photo 9 55_0100_Truck_2_Suspension_2_05_20_08.jpg



 $Photo\ 10\ 55_0100_Truck_2_Suspension_3_05_20_08.jpg$

ETG LTPP CLASS SCHEME, MOD 3

Axle 1 Weight Min *						2.5				2.5	3.5	3,5			2.5	3.5	3.0	3.5		2.5	3.5	5.0	3.5	3.5	3.5	5.0	5.0	5.0	5.0	5.0
Gross Weight Min-Max		0.10-3.00	1.00-7.99	1.00-7.99	12.00 >	8.00 >	1.00-11.99	1.00-11.99	20.00 >	12,00-19,99	12.00 >	20.00 >	1.00-11.99	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20,00 >	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20.00>	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >	20.00>	20.00 >
Spacing 8																														3.00-45.00
Spacing 7																													3.00-45.00	3.00-45.00
Spacing 6	77718								312.00						***************************************													3.00-45.00	3.00-45.00	3.00-45.00
Spacing 5						700000000000000000000000000000000000000																				2.50-10.99	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 4																			1.00-11.99	1.00-11.99	2.50-6.30	2.50-11.99	12.00-27.00	2.50-6.30	11.00-26.00	2.50-11.99	6.00-24.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 3			7,000,000										1.00-11.99	1.00-11.99	1.00-20.00	2.50-12.99	13.00-50.00	2.50-20.00	1.00-11.99	1.00-25.00	2.50-6.29	6.30-65.00	6.30-50.00	2.50-6.30	6.00-20.00	6.10-50.00	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 2							6.00-25.00	6.00-25.00	3.00-7.00	6.30-30,00	2.50-6.29	11.00-45.00	6.00-30.00	6.00-30.00	6.30-40.00	2.50-6.29	2.50-6.29	8.00-45.00	6.00-25.00	6.30-35.00	2.50-6.29	2.50-6.29	2.50-6.29	16.00-45.00	11.00-26.00	2.50-6.30	2.50-6.30	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 1		1.00-5.99	6,00-10,10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-23.09	6.00-23.09	6.00-10.10	10.11-23.09	6.00-26.00	6.00-23.09	6.00-26.00	6.00-26.00	10.11-23.09	6.00-23.09	6.00-23.09	6.00-30.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-26.00	6.00-26.00	6.00-45.00	6.00-45.00	6.00-45.00
No. Axles		7	2	7	2	7	3	3	æ	33	e	3	4	4	4	4	4	4	ĸ	\$	S	w	\$	5	5	9	9	<u>r</u>	x	6
Vehicle Type	1	Motorcycle	Passenger Car	Other (Pickup/Van)	Bus	2D Single Unit	Car w/1 Axle Trailer	Other w/ I Axle Trailer	Bus	2D w/ 1 Axie Trailer	3 Axle Single Unit	Semi, 2S1	Car w/2 Axle Trailer	Other w/ 2 Axle Trailer	2D w/ 2 Axle Trailer	4 Axle Single Unit	Semi, 3SI	Semi, 2S2	Other w/ 3 Axle Trailer	2D w/ 3 Axle Trailer	5 Axle Single Unit	Semi, 3S2	Truck+FullTrailer (3-2)	Semi, 2S3	Semi+FullTrailer, 2S12	Semi, 3S3	Semi+Full Trailer, 3S12	7 Axle Multi's	8 Axle Multi's	9 Axle Multi's
Class			7	60	4	S	7	6	4	'n	9	∞	7	3	S	-	%	×	3	w		6	6	6	=	10	12	13	13	13

Spacings in feet Weights in kips (Lbs/1000)
* Suggested Axle 1 minimum weight threshold if allowed by WIM system's class algorithm programming

System Operating Parameters

Wisconsin SPS-1 (Lane 1)

Calibration Factors for Sensor #1

Validation Visit	May 21, 2008	May 20, 2008*	November 27, 2007
Distance	372	372	372
Speed Bin			
80 kph	3131	3131	3296
88 kph	3162	3211	3381
96 kph	3164	3392	3571
104 kph	3210	3114	3278
112 kph	3099	3099	3262

Calibration Factors for Sensor #2

Validation Visit	May 21, 2008	May 20, 2008*	November 27, 2007
Distance			
Speed Bin			
80 kph	3302	3302	3476
88 kph	3336	3388	3566
96 kph	3338	3579	3767
104 kph	3386	3286	3459
112 kph	3269	3269	3441

^{*}Factor change specified for post-firmware start point.